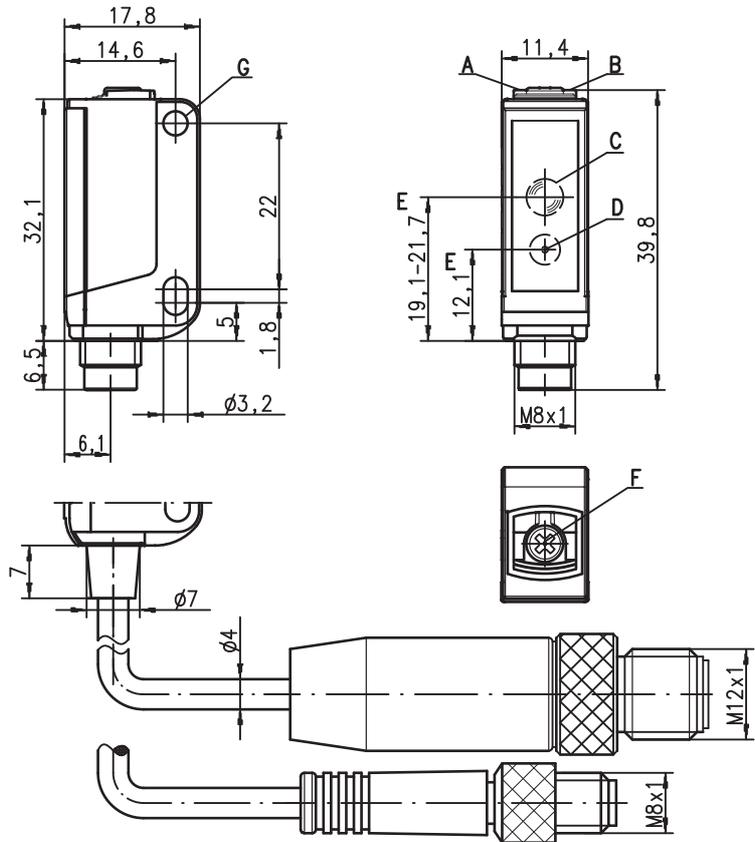


HRTL 3B Laser diffuse reflection light scanner with background suppression

en 03-2013/08 50114049



Dimensioned drawing



- A** Green indicator diode
- B** Yellow indicator diode
- C** Receiver
- D** Transmitter
- E** Optical axis
- F** 8-turn potentiometer for scanning range adjustment
- G** Mounting sleeve

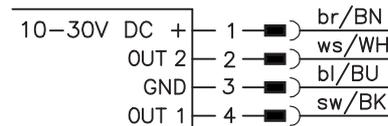
10 ... 400(500) mm
170(250) mm with
black/white error < 10%



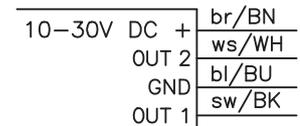
- Laser diffuse reflection light scanner with visible red light and adjustable background suppression
- Exact scanning range adjustment through 8-turn potentiometer
- Collimated light beam propagation with small beam diameter permits identical switching behavior within the specified scanning range
- Standard device in laser class 1 in accordance with EN 60825-1; extended scanning area with excellent black/white ratio in laser class 2
- High switching frequency and short response time for fast events and high-precision applications

Electrical connection

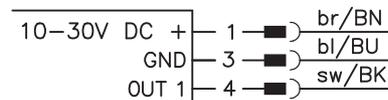
Plug connector, 4-pin



Cable, 4-wire



Plug connector, 3-pin



Accessories:

(available separately)

- Mounting systems (BT 3...)
- Cable with M8 or M12 connector (K-D ...)

We reserve the right to make changes • DS_HRTL3B_en_50114049.fm



Specifications

Optical data

Typ. scanning range limit ¹⁾	10 ... 400mm
Scanning range ²⁾	see tables
Adjustment range of the switching point	20 ... 400mm
Black/white error < 10% up to	170mm
Light beam diameter	approx. 1 mm, consistent
Light beam characteristic	collimated
Squint angle	typ. ± 2°
Light source ³⁾	laser, pulsed
Wavelength	650nm (visible red light)
Max. output power	≤ 0.81mW
Pulse duration	7µs

Laser class 2

5 ... 500mm
20 ... 500mm
250mm

≤ 3.3mW
7.6µs

Timing

Switching frequency	2,000Hz
Response time	0.25ms
Response jitter	typ. 65µs
Decay time	0.25ms
Delay before start-up	≤ 300ms

Electrical data

Operating voltage U_B ⁴⁾	10 ... 30VDC (incl. residual ripple)
Residual ripple	≤ 10% of U_B
Open-circuit current	≤ 20mA
Switching output	.../66 ⁵⁾ 2 push-pull switching outputs
	pin 2: PNP dark switching, NPN light switching
	pin 4: PNP light switching, NPN dark switching
	.../6 ⁵⁾ 1 push-pull switching output
	pin 4: PNP light switching, NPN dark switching
	$\geq (U_B - 2V) \leq 2V$
	max. 100mA
	adjustable via 8-turn potentiometer

Signal voltage high/low	
Output current	
Scanning range	

Indicators

Green LED	ready
Yellow LED	object detected - reflection

Mechanical data

Housing ⁶⁾	plastic (PC-ABS); 1 attachment sleeve, nickel-plated steel
Color	red RAL 3000
Optics cover	plastic (PMMA)
Fastening	through-holes for 2 x M3
Weight	with connector: 20g
	with 200mm cable and connector: 40g
	with 2m cable: 50g
	2m cable (cross section 4x0.20mm ²),
	connector M8 metal,
	0.2m cable with connector M8 or M12

Connection type

Environmental data

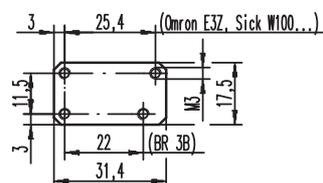
Ambient temp. (operation/storage)	-30°C ... +55°C / -40°C ... +70°C	
Protective circuit ⁷⁾	1, 2, 3	
VDE safety class	III	
Protection class	IP 67	
Laser class	1 in accordance with	2 in accordance with
	EN 60825-1:2007	EN 60825-1:2007
Standards applied	IEC 60947-5-2	
Certifications	UL 508 ⁴⁾	

- 1) Typ. scan. range limit/adjustment range: max. achievable scanning range/adjustment range for light objects (white 90%)
- 2) Scanning range: recommended scanning range for objects with different diffuse reflection
- 3) Average life expectancy 50,000h at an ambient temperature of 25°C
- 4) For UL applications: for use in class 2 circuits according to NEC only
- 5) The push-pull switching outputs must not be connected in parallel
- 6) Patent Pending Publ. No. US 7,476,848 B2
- 7) 1=overload protection, 2=polarity reversal protection, 3=short circuit protection for all transistor outputs

Remarks

Adapter plate:

BT 3.2 (part no. 501 03844) for alternate mounting on 25.4mm hole spacing (Omron E3Z, Sick W100...)



Tables

Models of laser class 1:

1	15	400
2	15	250
3	15	170

Models of laser class 2:

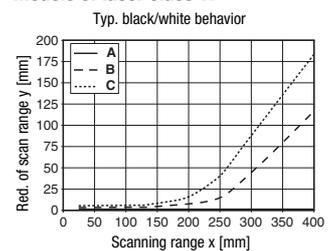
1	15	500
2	15	400
3	15	250

1	white 90%
2	gray 18%
3	black 6%

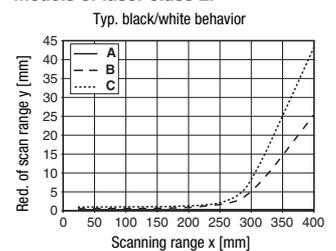
Scanning range [mm]

Diagrams

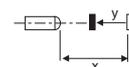
Models of laser class 1:



Models of laser class 2:



- A white 90%
- B gray 18%
- C black 6%



Remarks

Mounting system:



- ① = BT 3 (part no. 50060511)
- ②+③ = BT 3.1 ¹⁾ (part no. 50105585)
- ①+②+③ = BT 3B (part no. 50105546)

1) Packaging unit: PU = 10 pcs.

HRTL 3B Laser diffuse reflection light scanner with background suppression

Part number code

H	R	T	L	3	B	/	6	6	.	C	2	,	2	0	a	S	8	.	3
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Operating principle

HRT Diffuse reflection light scanners with background suppression

Operating principle

L Laser (red light)

Construction/version

3B Series 3B

Switching output/function (OUT 1: pin 4, OUT 2: pin 2)

/66 2 x push-pull transistor output, OUT 1: light switching, OUT 2: dark switching

/6 1 x push-pull transistor output, OUT 1: light switching, OUT 2: not connected (n. c.)

Equipment

N/A Laser class 1 in accordance with EN 60825-1

.C2 Laser class 2 in accordance with EN 60825-1

Electrical connection

N/A Cable, PVC, standard length 2000mm, 4-wire

-S8.3 M8 connector, 3 pin (plug)

-S8 M8 connector, 4 pin (plug)

,200-S8.3 Cable, PVC, length 200 mm with M 8 connector, 3 pin, axial (plug)

,200-S8 Cable, PVC, length 200 mm with M 8 connector, 4 pin, axial (plug)

,200-S12 Cable, PVC, length 200 mm with M 12 connector, 4 pin, axial (plug)

Order guide

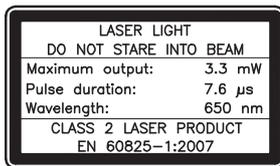
The sensors listed here are preferred types; current information at www.leuze.com

Order code	Part no.
HRTL 3B/66	50114760
HRTL 3B/66-S8	50114581
HRTL 3B/66, 200-S8	50114761
HRTL 3B/66, 200-S12	50114762
HRTL 3B/66-C2	50114763
HRTL 3B/66-C2-S8	50114582
HRTL 3B/66-C2, 200-S8	50114764
HRTL 3B/66-C2, 200-S12	50114765

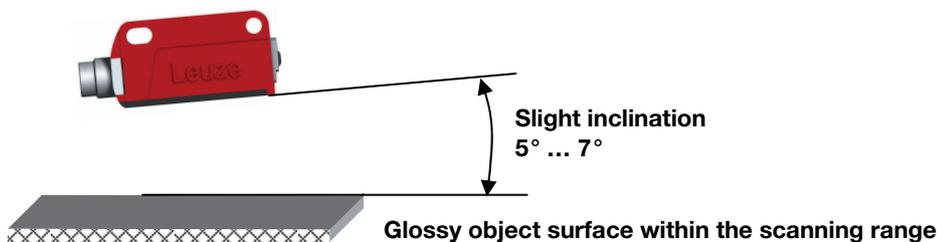
Application notes



- **Approved purpose:**
This product may only be used by qualified personnel and must only be used for the approved purpose. This sensor is not a safety sensor and is not to be used for the protection of persons.
- **Laser class 2 warning signs:**
It is important to attach the stick-on labels delivered with the device! If the signs could be covered due to the installation location of the device, attach them close to the device so that it is not possible to look into the laser beam when reading the notices.



- **Detection of glossy surfaces within the scanning range:**
When detecting glossy surfaces (e.g. metals), the light beam should not hit the object surface at a right angle. A slight inclination suffices to prevent undesirable direct reflections. The following rule of thumb applies: the smaller the scanning range, the larger the angle of the inclination (approx. 5° ... 7°).

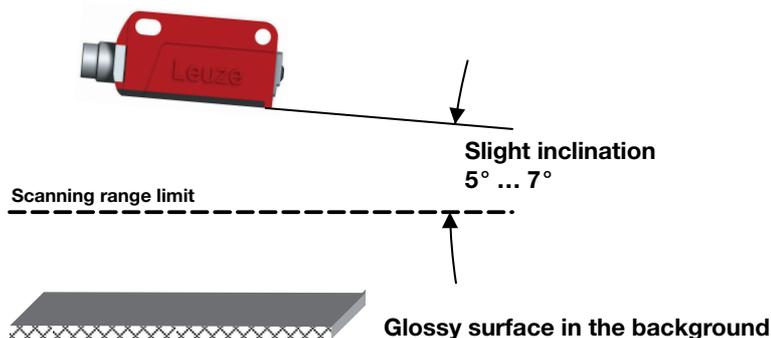


- **Avoiding interference from glossy surfaces in the background:**
If a glossy surface is in the background (distance larger than scanning range limit), reflections may cause interfering signals. These may be avoided by mounting the device at a slight angle (see figure below).



Attention!

It is imperative to note the task and the associated inclination of the scanner of approx. 5° ... 7°.



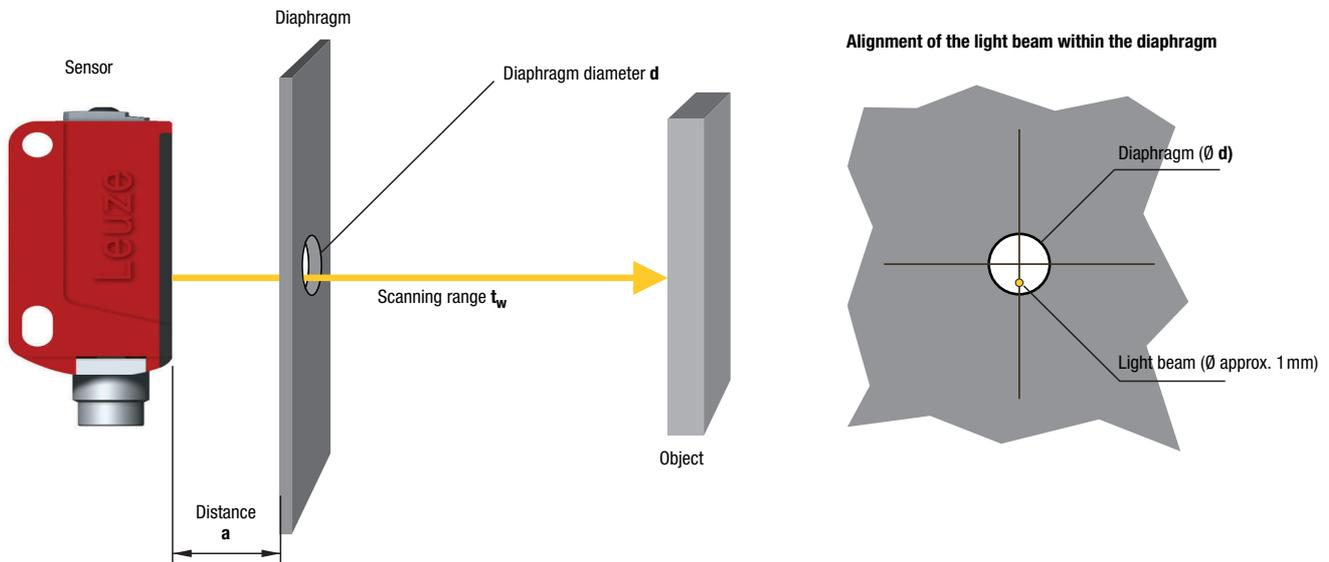
- Objects should only be moved in laterally from the right or left. Moving in objects from the connection side or operating side is to be avoided.
- Outside of the scanning range, the sensor operates as an energetic diffuse reflection light scanner. Light objects can still be reliably detected up to the scanning range limit.
- The sensors are equipped with effective measures for the maximum avoidance of mutual interference should they be mounted opposite one another. Opposite mounting of multiple sensors of the same type should, however, absolutely be avoided.

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Object detection behind diaphragms

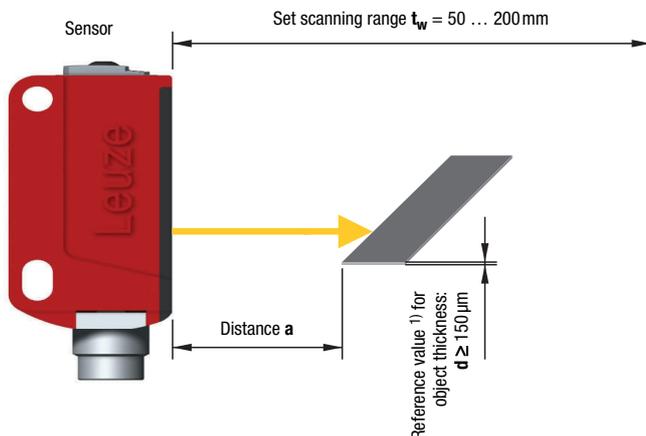
It is sometimes necessary to mount the sensor behind plant parts so that the light beam has to pass through an opening (diaphragm) that is as small as possible. Here, the detection depends, among other things, on set scanning range t_w , distance a between diaphragm and sensor, and diaphragm diameter d . Here are some reference values ¹⁾:

Distance a [mm] between sensor and diaphragm	Diaphragm diameter d [mm], dependent on scanning range t_w [mm] on a white object (90% diffuse reflection) set on the sensor		
	$t_w = 100$	$t_w = 200$	$t_w = 300$
10	10	10	10
30	8	8	9
50	7	8	9
80	6	7	8
100	6	6	8
120		6	8
150		5	6
180		5	6
200		5	6



Detection of smallest objects

The laser scanner can also detect very thin parts (e.g., sheet metal plates or wire). Detection here depends, among other things, on set scanning range t_w , distance a to the object, and object size/thickness d .



¹⁾  Reference values are not guaranteed properties. Due to the multitude of possible influencing factors, they must be confirmed in the application.

